

UNIT-1: Algorithm Basics & Analysis (Q1–Q17)

1. An algorithm must always
 - A) Be recursive
 - B) Terminate after finite steps
 - C) Use arrays
 - D) Be written in C

Answer: B
2. Which is NOT a characteristic of an algorithm?
 - A) Finiteness
 - B) Definiteness
 - C) Ambiguity
 - D) Effectiveness

Answer: C
3. Best-case complexity refers to
 - A) Maximum time
 - B) Minimum time
 - C) Average time
 - D) Random time

Answer: B
4. Worst-case complexity gives
 - A) Lower bound
 - B) Upper bound
 - C) Average bound
 - D) Exact bound

Answer: B
5. Big-O notation represents
 - A) Lower bound
 - B) Tight bound
 - C) Upper bound
 - D) Average bound

Answer: C
6. Ω (Omega) notation represents
 - A) Upper bound
 - B) Lower bound
 - C) Tight bound
 - D) Average bound

Answer: B
7. Θ (Theta) notation represents
 - A) Upper bound
 - B) Lower bound
 - C) Exact bound

D) Random bound
 Answer: C

8. Asymptotic analysis ignores
A) Input size
B) Constants
C) Algorithm logic
D) Loops
 Answer: B

9. Time-space tradeoff means
A) More time, more space
B) Less time, more space
C) More space, less time
D) Both B and C
 Answer: D

10. Empirical analysis involves
A) Mathematical proof
B) Running programs
C) Pseudocode
D) Recurrence relations
 Answer: B

11. Recursive algorithm analysis uses
A) Loops
B) Stack
C) Recurrence relations
D) Arrays
 Answer: C

12. Substitution method involves
A) Tree expansion
B) Guess and prove
C) Random trials
D) Tabulation
 Answer: B

13. Recursion tree method visualizes
A) Stack
B) Memory
C) Cost per level
D) Code flow
 Answer: C

14. Master's theorem applies to
A) Iterative loops
B) Sorting algorithms
C) Divide and conquer recurrences
D) Dynamic programming
 Answer: C

15. $T(n) = T(n/2) + O(1)$ gives

- A) $O(n)$
- B) $O(\log n)$
- C) $O(n \log n)$
- D) $O(n^2)$

 **Answer: B**

16. Performance measurement includes

- A) Only time
- B) Only space
- C) Time and space
- D) Cost

 **Answer: C**

17. Average-case analysis depends on

- A) Input distribution
- B) Hardware
- C) Compiler
- D) OS

 **Answer: A**

UNIT-2: Divide & Conquer and Heaps (Q18–Q35)

18. Divide and Conquer has how many steps?

- A) 2
- B) 3
- C) 4
- D) 5

 **Answer: B**

19. Binary search works on

- A) Unsorted array
- B) Sorted array
- C) Linked list only
- D) Tree only

 **Answer: B**

20. Time complexity of binary search is

- A) $O(n)$
- B) $O(n \log n)$
- C) $O(\log n)$
- D) $O(1)$

 **Answer: C**

21. Merge sort is

- A) In-place
- B) Unstable

C) Stable

D) Quadratic

Answer: C

22. Merge sort time complexity is

A) $O(n^2)$

B) $O(n \log n)$

C) $O(\log n)$

D) $O(n)$

Answer: B

23. Quick sort worst-case complexity is

A) $O(n \log n)$

B) $O(\log n)$

C) $O(n^2)$

D) $O(n)$

Answer: C

24. Quick sort is faster in practice because

A) No recursion

B) In-place

C) Less comparisons

D) Cache friendly

Answer: B

25. Linear-time selection algorithm finds

A) Maximum

B) Median

C) k-th smallest

D) Sum

Answer: C

26. Median of medians ensures

A) Best case

B) Average case

C) Worst-case linear time

D) Constant time

Answer: C

27. Strassen's algorithm improves

A) Space

B) Matrix addition

C) Matrix multiplication

D) Sorting

Answer: C

28. Strassen's time complexity is

A) $O(n^3)$

B) $O(n^2)$

C) $O(n^{2.81})$

D) $O(n \log n)$

Answer: C

29. Karatsuba algorithm is used for

- A) Division
- B) Sorting
- C) Fast multiplication
- D) Searching

Answer: C

30. Heap is a

- A) BST
- B) Complete binary tree
- C) Graph
- D) Array

Answer: B

31. Min heap property ensures

- A) Parent \geq children
- B) Parent \leq children
- C) Left $<$ right
- D) Sorted order

Answer: B

32. Build heap time complexity is

- A) $O(n \log n)$
- B) $O(\log n)$
- C) $O(n)$
- D) $O(n^2)$

Answer: C

33. Heap sort time complexity is

- A) $O(n^2)$
- B) $O(n \log n)$
- C) $O(\log n)$
- D) $O(n)$

Answer: B

34. Heap sort is

- A) Stable
- B) Unstable
- C) Recursive
- D) Quadratic

Answer: B

35. Priority queue is efficiently implemented using

- A) Stack
- B) Queue
- C) Heap
- D) Tree

Answer: C

UNIT-3: Design Techniques & Greedy (Q36–Q52)

36. Brute-force approach tries

- A) Best option
- B) Greedy option
- C) All possibilities
- D) Random option

 **Answer: C**

37. Greedy algorithm makes

- A) Global optimal choice
- B) Local optimal choice
- C) Random choice
- D) Exhaustive choice

 **Answer: B**

38. Greedy algorithms always give optimal solution

- A) True
- B) False

 **Answer: B**

39. Dynamic programming is useful when subproblems

- A) Are independent
- B) Overlap
- C) Are random
- D) Are infinite

 **Answer: B**

40. Backtracking is used for

- A) Optimization
- B) Enumeration
- C) Feasibility problems
- D) Sorting

 **Answer: C**

41. Branch and Bound is used for

- A) Feasibility problems
- B) Optimization problems
- C) Sorting
- D) Searching

 **Answer: B**

42. MST stands for

- A) Minimum Shortest Tree
- B) Minimum Spanning Tree
- C) Maximum Spanning Tree
- D) Minimum Search Tree

 **Answer: B**

43. Prim's algorithm is based on

- A) Divide and conquer

- B) Dynamic programming
- C) Greedy approach
- D) Backtracking

 **Answer: C**

44. Kruskal's algorithm uses

- A) DFS
- B) Union-Find
- C) BFS
- D) Stack

 **Answer: B**

45. Fractional knapsack uses

- A) DP
- B) Greedy
- C) Backtracking
- D) Branch and Bound

 **Answer: B**

46. 0–1 Knapsack uses

- A) Greedy
- B) DP
- C) Brute force
- D) Random

 **Answer: B**

47. Job sequencing problem maximizes

- A) Time
- B) Weight
- C) Profit
- D) Cost

 **Answer: C**

48. Huffman coding is used for

- A) Encryption
- B) Compression
- C) Sorting
- D) Searching

 **Answer: B**

49. Huffman coding generates

- A) Fixed length codes
- B) Prefix codes
- C) Binary trees only
- D) Hash codes

 **Answer: B**

50. Dijkstra's algorithm finds

- A) MST
- B) All-pairs shortest path
- C) Single-source shortest path

D) Longest path

Answer: C

51. Greedy fails when

- A) Optimal substructure absent
- B) Overlapping subproblems exist
- C) Local choice is not global optimal
- D) Input is sorted

Answer: C

52. Backtracking prunes solutions that are

- A) Optimal
- B) Infeasible
- C) Expensive
- D) Recursive

Answer: B

UNIT-4: Dynamic Programming & Heuristics (Q53–Q68)

53. DP stores results of

- A) Independent subproblems
- B) Overlapping subproblems
- C) Random problems
- D) Large problems

Answer: B

54. DP avoids

- A) Recursion
- B) Re-computation
- C) Iteration
- D) Optimization

Answer: B

55. Fibonacci using DP runs in

- A) $O(2^n)$
- B) $O(n^2)$
- C) $O(n)$
- D) $O(\log n)$

Answer: C

56. Matrix Chain Multiplication minimizes

- A) Time
- B) Memory
- C) Scalar multiplications
- D) Matrices

Answer: C

57. LCS stands for

- A) Longest Common Subsequence
- B) Largest Common String
- C) Least Common Subsequence
- D) Longest Continuous String

Answer: A

58. LCS is used in

- A) Sorting
- B) Scheduling
- C) Bioinformatics
- D) Encryption

Answer: C

59. TSP belongs to

- A) P
- B) NP-complete
- C) NP-hard
- D) Linear time

Answer: C

60. Rod cutting problem aims to

- A) Minimize cost
- B) Maximize profit
- C) Sort rods
- D) Pack rods

Answer: B

61. Bin packing problem is

- A) Polynomial
- B) NP-hard
- C) Trivial
- D) Constant time

Answer: B

62. DP vs Divide & Conquer: DP

- A) Recomputes results
- B) Stores results
- C) Uses no recursion
- D) Uses greedy

Answer: B

63. Heuristics provide

- A) Exact solution
- B) Optimal solution always
- C) Approximate solution
- D) Worst solution

Answer: C

64. Heuristics are used for

- A) Easy problems
- B) NP-hard problems

- C) Linear problems
- D) Trivial problems

Answer: B

65. Heuristic solutions are

- A) Slow
- B) Guaranteed optimal
- C) Fast
- D) Exact

Answer: C

66. TSP DP solution complexity is

- A) $O(n^2)$
- B) $O(n^3)$
- C) $O(n \cdot 2^n)$
- D) $O(n!)$

Answer: C

67. Bin packing greedy approach is

- A) First fit
- B) Best fit
- C) Worst fit
- D) All

Answer: D

68. DP table size depends on

- A) Hardware
- B) Input size
- C) OS
- D) Language

Answer: B

UNIT-5: Graph & Tree Algorithms (Q69–Q85)

69. Graph can be represented using

- A) Matrix
- B) List
- C) Both
- D) None

Answer: C

70. Adjacency matrix space is

- A) $O(V)$
- B) $O(E)$
- C) $O(V^2)$
- D) $O(V+E)$

Answer: C

71. BFS uses

- A) Stack
- B) Queue
- C) Recursion
- D) Heap

Answer: B

72. DFS uses

- A) Queue
- B) Heap
- C) Stack
- D) Array

Answer: C

73. BFS finds

- A) Any path
- B) Shortest path in unweighted graph
- C) Longest path
- D) MST

Answer: B

74. DFS is used for

- A) Shortest path
- B) Topological sort
- C) MST
- D) Network flow

Answer: B

75. Bellman-Ford handles

- A) Positive weights only
- B) Negative weights
- C) No weights
- D) Zero weights

Answer: B

76. Bellman-Ford time complexity is

- A) $O(V^2)$
- B) $O(E \log V)$
- C) $O(VE)$
- D) $O(V^3)$

Answer: C

77. Dijkstra fails with

- A) Positive edges
- B) Negative edges
- C) Zero edges
- D) Weighted graphs

Answer: B

78. Dijkstra using heap runs in

- A) $O(V^2)$
- B) $O(E \log V)$

- C) $O(VE)$
- D) $O(V^3)$

Answer: B

79. Floyd-Warshall computes

- A) Single source shortest path
- B) MST
- C) All-pairs shortest path
- D) DFS

Answer: C

80. Floyd-Warshall time complexity is

- A) $O(V^2)$
- B) $O(E \log V)$
- C) $O(V^3)$
- D) $O(VE)$

Answer: C

81. Transitive closure finds

- A) Path length
- B) Reachability
- C) MST
- D) Degree

Answer: B

82. Topological sort is applicable to

- A) Cyclic graph
- B) DAG
- C) Tree
- D) Weighted graph

Answer: B

83. Network flow algorithm computes

- A) Shortest path
- B) Maximum flow
- C) MST
- D) Cycle

Answer: B

84. Ford-Fulkerson uses

- A) Greedy
- B) BFS
- C) DFS
- D) Residual graph

Answer: D

85. Connected components are found using

- A) DFS or BFS
- B) Dijkstra
- C) Floyd
- D) Kruskal

Answer: A

UNIT-6: Complexity Classes & Advanced Topics (Q86–Q100)

86. Tractable problems are solvable in

- A) Exponential time
- B) Polynomial time
- C) Infinite time
- D) Random time

 **Answer: B**

87. Intractable problems require

- A) Polynomial time
- B) Constant time
- C) Exponential time
- D) Linear time

 **Answer: C**

88. Class P problems are

- A) Hard
- B) Easy
- C) Undecidable
- D) Random

 **Answer: B**

89. Class NP problems are

- A) Solvable in polynomial time
- B) Verifiable in polynomial time
- C) Undecidable
- D) Unsolvable

 **Answer: B**

90. NP-complete problems are

- A) Easiest
- B) Hardest in NP
- C) Polynomial
- D) Linear

 **Answer: B**

91. NP-hard problems may not be

- A) Hard
- B) Verifiable
- C) In NP
- D) Polynomial

 **Answer: C**

92. Cook's theorem states that

- A) $P = NP$

- B) SAT is NP-complete
- C) NP is empty
- D) TSP is polynomial

 **Answer: B**

93. SAT stands for

- A) Satisfiability
- B) Simple Algorithm Test
- C) System Analysis Tool
- D) Search Algorithm Test

 **Answer: A**

94. Reduction technique is used to

- A) Simplify algorithm
- B) Prove NP-completeness
- C) Optimize code
- D) Sort data

 **Answer: B**

95. Polynomial-time reduction means

- A) Exponential transformation
- B) Fast transformation
- C) Slow transformation
- D) Random transformation

 **Answer: B**

96. Approximation algorithms give

- A) Exact solution
- B) Near-optimal solution
- C) Worst solution
- D) Random solution

 **Answer: B**

97. Performance ratio measures

- A) Speed
- B) Memory
- C) Quality of approximation
- D) Randomness

 **Answer: C**

98. Randomized algorithms use

- A) Deterministic choices
- B) Random numbers
- C) DP
- D) Greedy

 **Answer: B**

99. Las Vegas algorithms

- A) Give wrong answers
- B) Always correct but random time
- C) Always fast but wrong

D) Are deterministic

Answer: B

100. Monte Carlo algorithms

A) Always correct

B) May give incorrect answer

C) Deterministic

D) Use DP

Answer: B

If you want next:

- **Answer-only revision sheet**
- **Unit-wise MCQ test PDFs**
- **Important repeated exam MCQs**
- **Short notes for last-day revision**

Just tell me 